# The FMM for 3D Helmholtz Equation

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## Reference

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Fast Multipole Methods for Solution of the Helmholtz Equation in Three Dimensions

Academic Press, Oxford (2004) (in process).

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- Helmholtz Equation
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- Fast Translation Methods
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# Helmholtz Equation

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$$\lim_{\omega \to \infty} \left[ r \left( \frac{\partial \psi_{scat}}{\partial r} - i k \psi_{scat} \right) \right] = 0.$$

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#### Distributions of Monopoles and Dipoles

Volume source distribution:

$$\psi(\mathbf{y}) = \sum_{j=1}^{N} Q_j G(\mathbf{x}_j, \mathbf{y}), \quad \mathbf{y} \in \mathbb{R}^3 \setminus \{\mathbf{x}_j\},$$

$$\psi(\mathbf{y}) = \int_{\overline{\Omega}} q(\mathbf{x}) G(\mathbf{x}, \mathbf{y}) dV(\mathbf{x}), \quad \mathbf{y} \in \Omega, \quad \overline{\Omega} \cap \Omega = \emptyset.$$

Single layer potential:

$$\psi(\mathbf{y}) = \int_{S} q_{\sigma}(\mathbf{x}) G(\mathbf{x}, \mathbf{y}) dS(\mathbf{x}), \quad \mathbf{y} \in \Omega, \quad S = \partial \Omega.$$

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Double layer potential:

$$\psi(\mathbf{y}) = \int_{S} q_{\mu}(\mathbf{x}) \frac{\partial G(\mathbf{x}, \mathbf{y})}{\partial n(\mathbf{x})} dS(\mathbf{x}), \quad \mathbf{y} \in \Omega, \quad S = \partial \Omega.$$





### **Spherical Bessel Functions**



 $h_n(\rho) = j_n(\rho) + i y_n(\rho)$ 

$$j_0(\rho) = \frac{\sin\rho}{\rho}, \quad j_1(\rho) = \frac{\sin\rho}{\rho^2} - \frac{\cos\rho}{\rho},$$
$$j_2(\rho) = \left(\frac{3}{\rho^3} - \frac{1}{\rho}\right)\sin\rho - \frac{3}{\rho^2}\cos\rho,$$
$$y_0(\rho) = -\frac{\cos\rho}{\rho}, \quad y_1(\rho) = -\frac{\cos\rho}{\rho^2} - \frac{\sin\rho}{\rho},$$
$$y_2(\rho) = \left(-\frac{3}{\rho^3} + \frac{1}{\rho}\right)\cos\rho - \frac{3}{\rho^2}\sin\rho.$$

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$$\begin{aligned} & \text{Expansions} \\ \psi(\mathbf{r}) = \sum_{n=0}^{\infty} \sum_{m=-n}^{n} A_n^m F_n^m(\mathbf{r}) = \sum_{m=-\infty}^{\infty} \sum_{n=|m|}^{\infty} A_n^m F_n^m(\mathbf{r}), \quad F = S, R, \quad A_n^m \in \mathbb{C}. \end{aligned}$$

Absolute and uniform convergence

$$\forall \epsilon > 0, \quad \exists p(\epsilon), \quad \left| \psi(\mathbf{r}) - \sum_{n=0}^{p-1} \sum_{m=-n}^{n} A_n^m F_n^m(\mathbf{r}) \right| < \epsilon, \quad \forall \mathbf{r} \in \Omega,$$

and

$$\forall \epsilon > 0, \quad \exists p(\epsilon), \quad \sum_{n=p}^{\infty} \sum_{m=-n}^{n} |\mathcal{A}_{n}^{m} F_{n}^{m}(\mathbf{r})| < \epsilon, \quad \forall \mathbf{r} \in \Omega.$$

Plane Wave expansion:

$$e^{i\mathbf{k}\cdot\mathbf{r}} = 4\pi \sum_{n=0}^{\infty} \sum_{m=-n}^{n} i^n Y_n^{-m}(\theta_k, \varphi_k) R_n^m(\mathbf{r}),$$
  
$$\mathbf{k} = k\mathbf{s}, \quad \mathbf{s} = (\sin\theta_k \cos\varphi_k, \sin\theta_k \sin\varphi_k, \cos\theta_k).$$

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## Matrix Translations

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## **Translation Methods**

- O(p<sup>5</sup>): Matrix Translation with Computation of Matrix Elements Based on Clebsch-Gordan Coefficients;
- O(p<sup>4</sup>) (Low Asymptotic Constant): Matrix Translation with Recursive Computation of Matrix Elements
- O(p<sup>3</sup>) (Low Asymptotic Constants):

Rotation-Coaxial Translation Decomposition with Recursive Computation of Matrix Elements;
 Sparse Matrix Decomposition;

•  $O(p^2 log^{\beta} p)$ 

 Rotation-Coaxial Translation Decomposition with Structured Matrices for Rotation and Fast Legendre Transform for Coaxial Translation;

- □ Translation Matrix Diagonalization with Fast Spherical Transform;
- □ Asymptotic Methods;
- Diagonal Forms of Translation Operators with Spherical Filtering.

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# O(p<sup>3</sup>) Methods

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#### **Sparse Matrix Decomposition**

$$(\mathbf{R}|\mathbf{R})(\mathbf{t}) = (\mathbf{S}|\mathbf{S})(\mathbf{t}) = \sum_{n=0}^{\infty} \frac{(kt)^n}{n!} \mathbf{D}_{\mathbf{t}}^n = e^{kt\mathbf{D}_{\mathbf{t}}} = \Lambda_r(kt, -i\mathbf{D}_{\mathbf{t}})$$

$$(\mathbf{S}|\mathbf{R})(\mathbf{t}) = \Lambda_s(kt, -i\mathbf{D}_t)$$

Matrix-vector products with these matrices computed recursively

$$\Lambda_r(kt, -i\mathbf{D}_t) = \sum_{n=0}^{\infty} (2n+1)i^n j_n(kt) P_n(-i\mathbf{D}_t)$$

$$\Lambda_s(kt, -i\mathbf{D}_t) = \sum_{n=0}^{\infty} (2n+1)i^n h_n(kt) P_n(-i\mathbf{D}_t).$$

$$\Lambda_s(kt, -i\mathbf{D}_t) = \sum_{n=0}^{\infty} (2n+1)i^n h_n(kt) P_n(-i\mathbf{D}_t)^*.$$

 $(\mathbf{D}_{\mathbf{t}}\mathbf{C})_{n}^{m} = \frac{1}{2t} \Big[ (t_{x} + it_{y}) \Big( C_{n-1}^{m+1}b_{n}^{m} - C_{n+1}^{m+1}b_{n+1}^{-m-1} \Big) + (t_{x} - it_{y}) \Big( C_{n-1}^{m-1}b_{n}^{-m} - C_{n+1}^{m-1}b_{n+1}^{m-1} \Big) \Big]$  $+ \frac{t_z}{t} (a_n^m C_{n+1}^m - a_{n-1}^m C_{n-1}^m), \qquad m = 0, \pm 1, \pm 2, \dots, \quad n = |m|, |m| + 1, \dots$ 

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Method of Signature Function  
(Diagonal Forms of the Translation Operator)
$$\psi(\mathbf{r}) = \frac{1}{4\pi} \int_{S_{u}} e^{iks\cdot\mathbf{r}\cdot\Psi}(\mathbf{s}) dS(\mathbf{s}),$$
Regular Solution $\psi^{(p)}(\mathbf{r}) = \frac{1}{4\pi} \int_{S_{u}} \Lambda_{s}^{(p)}(\mathbf{r}; \mathbf{s}) \Psi(\mathbf{s}) dS(\mathbf{s}),$ Singular Solution $\Lambda_{r}(\mathbf{r}; \mathbf{s}) = \sum_{n=0}^{\infty} (2n+1)i^{n}j_{n}(kr)P_{n}(\frac{\mathbf{r}\cdot\mathbf{s}}{r})$  $\Lambda_{s}^{(p)}(\mathbf{r}; \mathbf{s}) = \sum_{n=0}^{p-1} (2n+1)i^{n}h_{n}(kr)P_{n}(\frac{\mathbf{r}\cdot\mathbf{s}}{r}).$  $\widehat{\Psi}(\mathbf{s}) = (S|S)(\mathbf{t})[\Psi(\mathbf{s})] = (\mathcal{R}|\mathcal{R})(\mathbf{t})[\Psi(\mathbf{s})] = e^{iks\cdot\mathbf{t}}\Psi(\mathbf{s}),$  $\widehat{\Psi}_{(p)}(\mathbf{s}) = (S|\mathcal{R})(\mathbf{t})[\Psi(\mathbf{s})] = \Lambda_{s}^{(p)}(\mathbf{t}; \mathbf{s})\Psi(\mathbf{s}).$ CSCAMM FAM04: 04/19/2004

## Final Summation and Initial Expansion

$$\psi(\mathbf{r}) = \frac{1}{4\pi} \sum_{j=0}^{N_c-1} w_j e^{ik\mathbf{s}_j \cdot \mathbf{r}} \Psi(\mathbf{s}_j) + \epsilon_c, \quad \mathbf{s}_j \in S_u,$$

$$G(\mathbf{r} - \mathbf{r}_s) \rightleftharpoons \Psi_{(0)}(\mathbf{s}_j; \mathbf{r}_s - \mathbf{r}_*) = \frac{ik}{4\pi} e^{-ik\mathbf{s}_j \cdot (\mathbf{r}_s - \mathbf{r}_*)}$$

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## Deficiencies

- Low Frequencies;
- High Frequencies;
- Constant p;
- Instabilities after two or three levels of translations.

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## Methods to Fix:

- Use of Band-limited functions;
- Error control via band-limits;
- Requires filtering procedures (complexity O(p<sup>2</sup>log<sup>2</sup>p) or O(p<sup>2</sup>logp)) with large asymptotic constants;
- The length of the representation is changed via interpolation/anterpolation procedures.

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## **Error Bounds**

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Krylov Subspace Method (GMRES)

Reflection (Simple Iteration) Method:

$$\begin{split} \mathbf{A}_{j}^{(q)} &= \mathbf{T}^{(q)} \Big[ \mathbf{E}^{(in)}(\mathbf{r}_{q}') + \mathbf{B}_{j}^{(q)} \Big], \\ \mathbf{B}_{j+1}^{(q)} &= \sum_{p \neq q} (\mathbf{S} | \mathbf{R}) (\mathbf{r}_{q}' - \mathbf{r}_{p}') \mathbf{A}_{j}^{(p)}, \\ \Big| \mathbf{A}_{j}^{(q)} - \mathbf{A}_{j+1}^{(q)} \Big| &< \epsilon, \quad q = 1, ..., N. \end{split}$$

General Formulation (used in GMRES)

$$\mathbf{I} - \mathbf{T}^{(q)} \sum_{p \neq q} (\mathbf{S} | \mathbf{R}) (\mathbf{r}'_q - \mathbf{r}'_p) \mathbf{A}^{(q)} = \mathbf{T}^{(q)} \mathbf{E}^{(in)} (\mathbf{r}'_q).$$

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More About This Problem in Our Talk Next Week

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