

# The KIAPS Observation Processing System Development for the Data Assimilation

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Detect sur. 4-point

search nearest grid point

(lower-left to the obs.

cal. weighting function

Detected grid info.

weighting functions

- grid points

> Cal. vert.-weight β

Cal. ∏ at theta-level

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# Introduction

The Korea Institute of Atmospheric Prediction Systems (KIAPS) was founded in 2011-2019) project to develop Korea's own global Numerical Weather Prediction (NWP) system.

Most meteorological observations contain errors and those errors varies depending on the type of observation.

Observation Processing System has a critical role which figures out the observation errors and corrects or filter out the bias from the raw data.

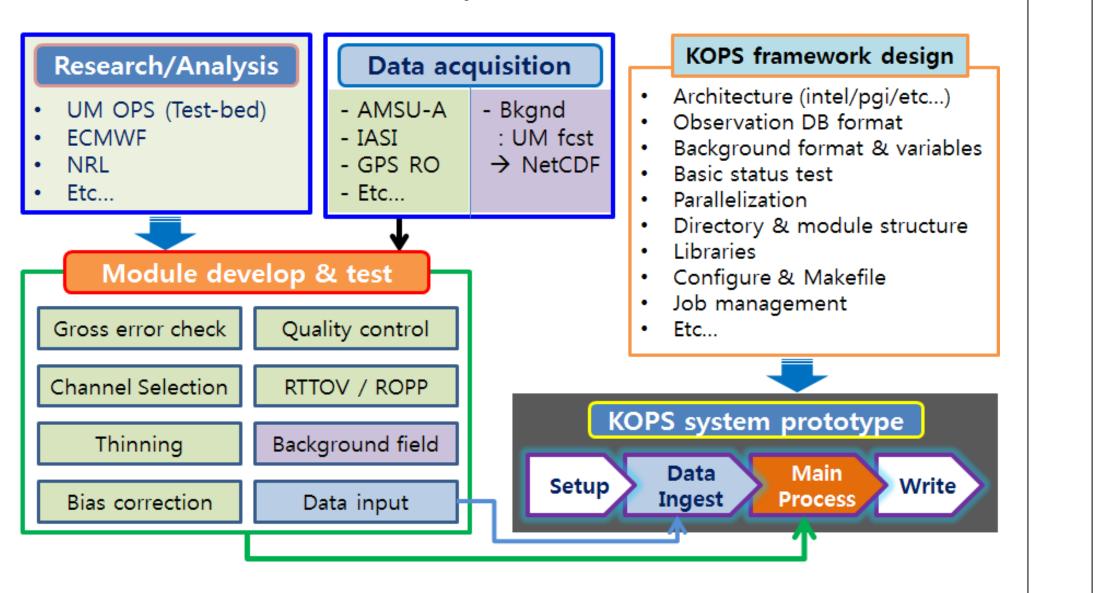
The KIAPS data assimilation team has been developing the KIAPS Observation Processing System (KOPS) to provide KIAPS data assimilation system with optimal observations.

At this stage, a prototype framework for the satellite radiance data (AMSU-A and IAIS), SONDE (Temp, Pilot, Wind profiler), and Global Positioning System Radio Occultation (GPS-RO) data processing system has been developed.

# **Development of the KOPS framework**

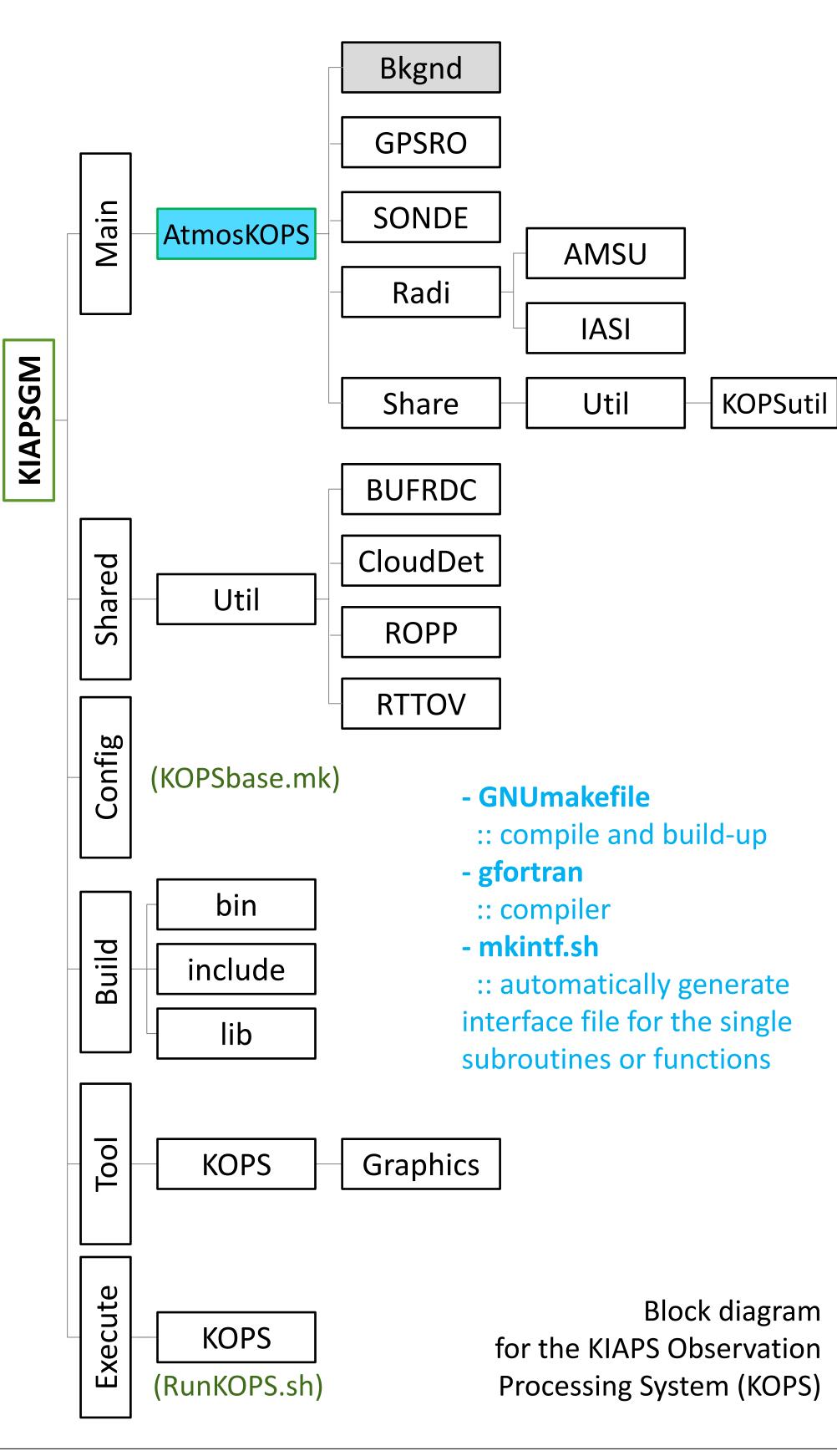
### KOPS design and development plan

- study and analyze observation processing systems of advanced operational institutes
- (MetOffice, ECMWF, NRL, etc...)
- develop individual modules for the specific processing steps
- (err check, QC, thinning, BC, obs. operators, ...)
- acquisition of observation database (BUFR) and model forecast (KMA operational forecast model)



### KOPS in the KIAPSGM framework

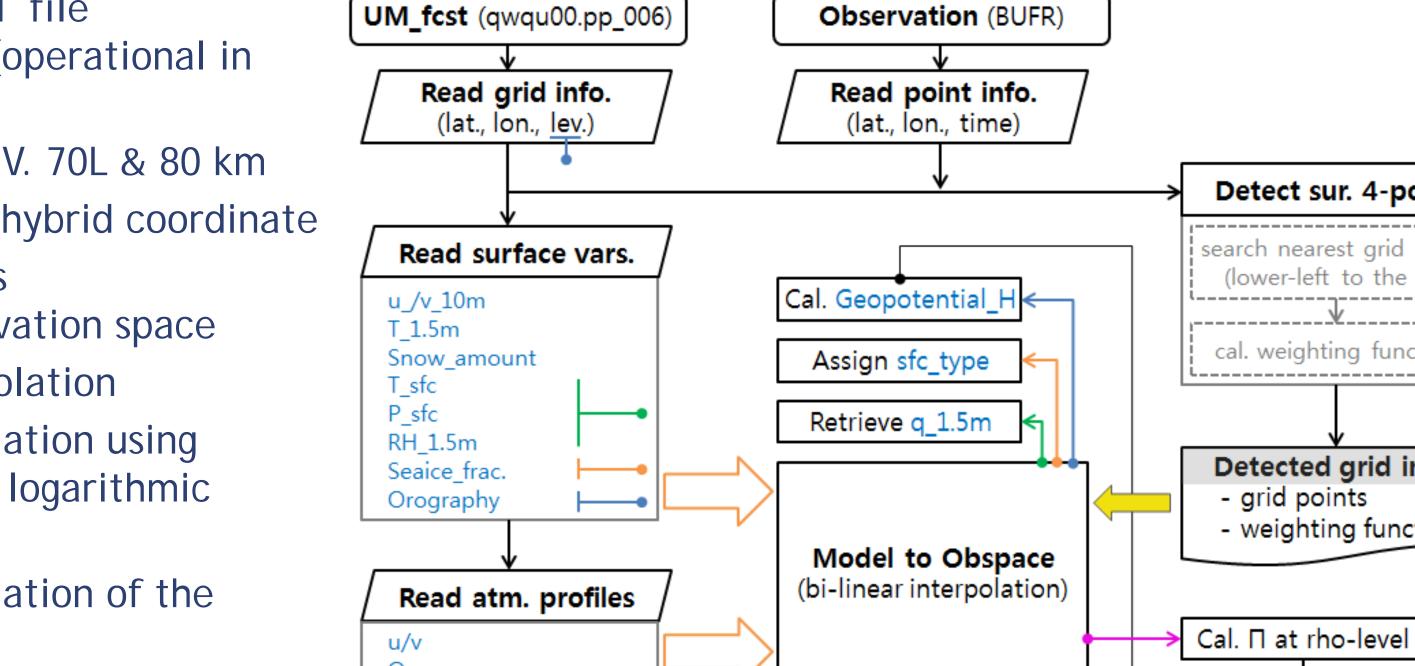
- based on the KIAPS Global NWP Model (KIAPSGM) framework
- library share with assimilation system on the observation operators



# **Development of Background ingest process**

## Background ingest process

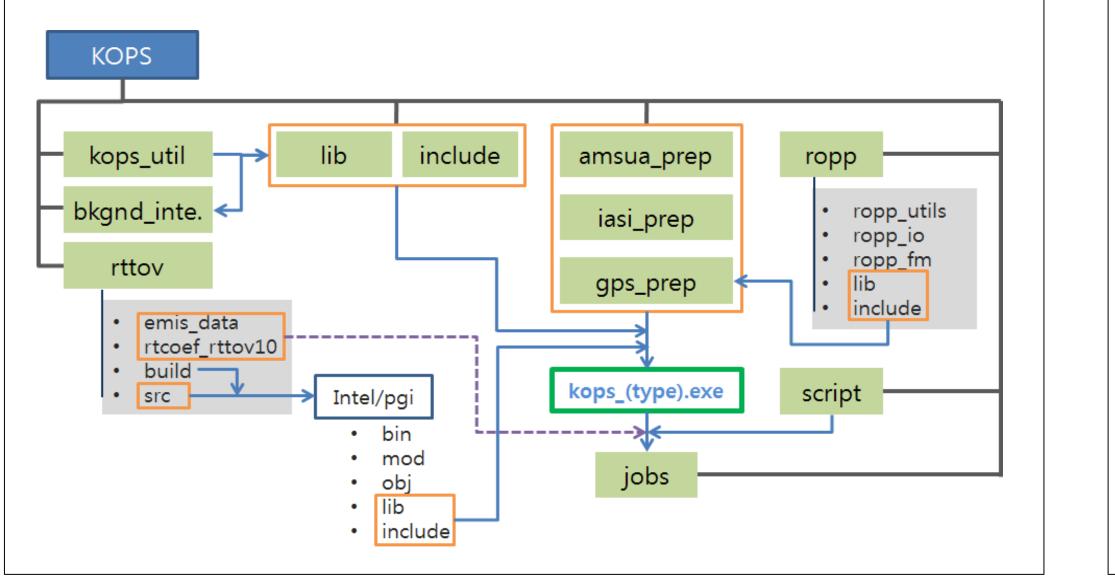
- using netcdf type background file converted from UM forecast (operational in KMA, pp type)
- global model / H. ~25km / V. 70L & 80 km
- Arakawa-C staggered grid / hybrid coordinate
- interpolate forecast variables from model grid to the observation space
- horizontal : bi-linear interpolation
- vertical : weighting interpolation using geopotential height and /or logarithmic pressure
- variable transform and calculation of the
- 2<sup>nd</sup> (additional) variables
- $\cdot$  e.g.:: RH  $\rightarrow$  Q /  $\theta \rightarrow$  T / ...
- P (at rho-level) - calculate geopotential height at each rho and theta-level



θ (at theta-level)

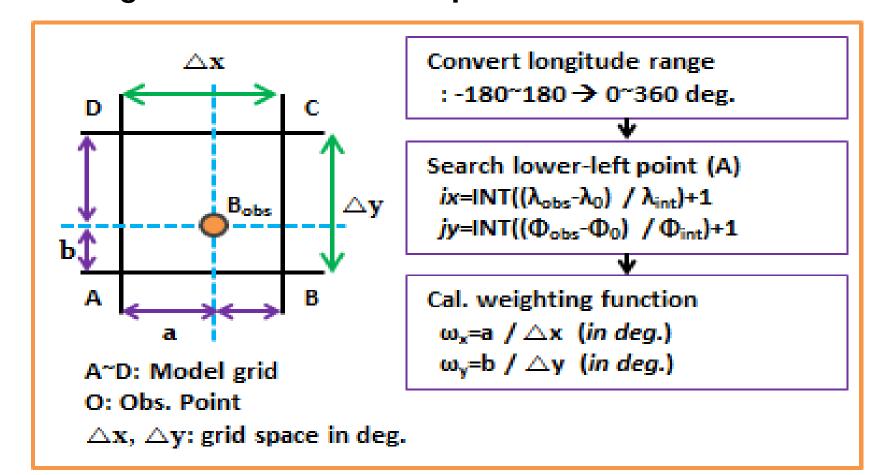
### Prototype of KOPS framework

- construction of directory structure according to the function and observation types
- build-up libraries: modules and open packages (open packages: RTTOV\_v10, ROPP, BUFRDC)
- shell scripts for the task management



### Horizontal interpolation method

### 1<sup>st</sup> stage: bi-linear interpolation



### $B_{obs} = A(1-\omega_x)(1-\omega_y) + B(\omega_x)(1-\omega_y) +$ $C(\omega_x)(\omega_y)$ + D(1- $\omega_x$ )( $\omega_y$ ))

- disregard the difference of vertical height between each grid points (A~D) - vertical height at the B<sub>obs</sub> point are assigned by mean of the grid points height

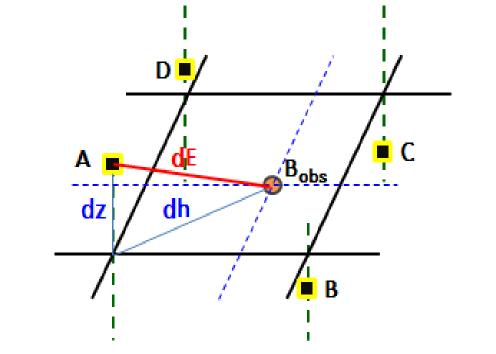
Arctic\_Ocean

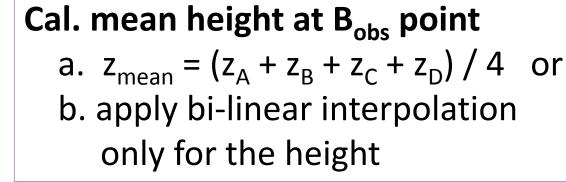
### Improvement of interpolation method

- 3D-interpolation method using euclidian distance - reflection of vertical height differences

Conv.  $\theta \rightarrow$  Temp.

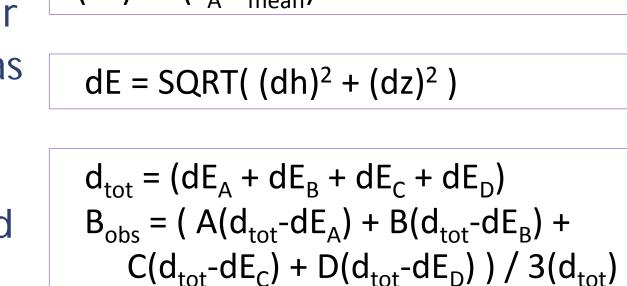
Ret. P at theta-leve



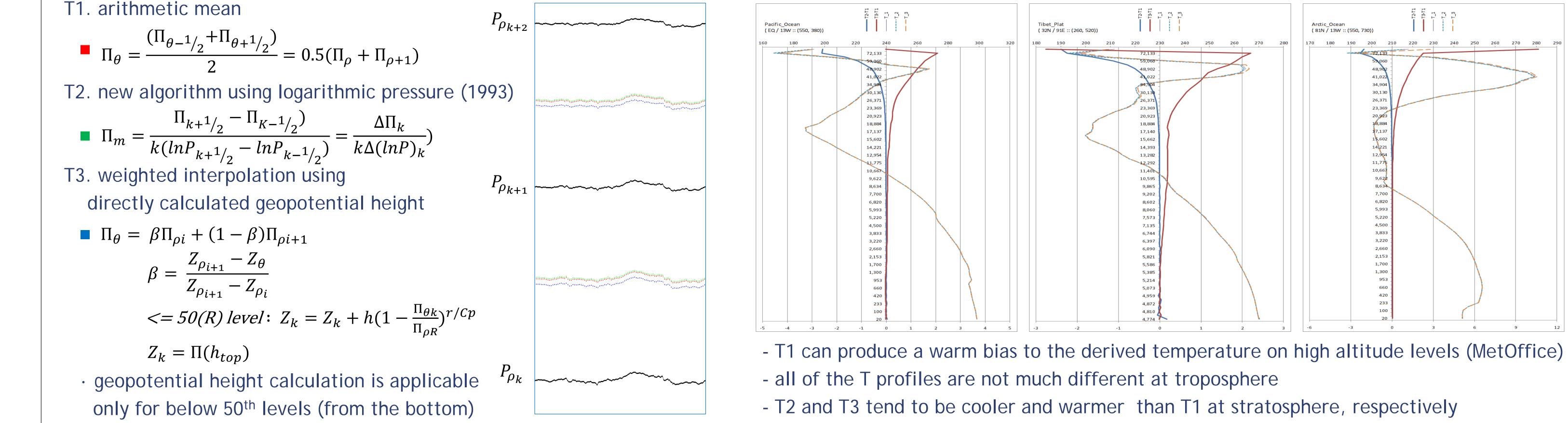


 $(dh)^2 = (\lambda_{obs} - \lambda_A)^2 + (\Phi_{obs} - \Phi_A)^2$  $(dz)^2 = (z_A - z_{mean})^2$ 

- not only for the regular grid background such as UM fcst. but also nonregular such as cubedsphere grid background could be processed



### Summary and future plans Vertical interpolation methods Summary Exner pressure at theta-level Comparison of the temperature profiles - KIAPS Observation Processing System (KOPS)



framework has been developing based on the KIAPS Global NWP Model (KIAPSGM) framework - Improved H. interpolation method are applied on the background ingest module and the T-profiles according to the V. interpolation methods are compared each other Future plan - development of the "grid point search module" for the treatment of irregular grid model data to cope with the Cubed-Sphere grid (KIAPSGM) Conv. Lat./Lon. To grid number  $ix=INT((\lambda_{model}-\lambda_0) / \lambda_{int})+1$ c=INT(rd x cos( $\Phi_{model}$  x d2r)  $jy=INT((\Phi_{model}-\Phi_0) / \Phi_{int})+1$  $y=INT(rd \times sin(\Phi_{model} \times d2r))$ 

> - development of the processing module for the hyperspectral IR satellite observation, MW, geostationary satellite data, and synoptic observations